

1.5

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Important differential operators:

1) Divergence.

If $\vec{F}(x, y, z) = (F_1(x, y, z), F_2(x, y, z), F_3(x, y, z))$
 $\vec{x} = (x, y, z)$

$$\nabla \cdot \vec{F} = \frac{\partial F_1}{\partial x}(\vec{x}) + \frac{\partial F_2}{\partial y}(\vec{x}) + \frac{\partial F_3}{\partial z}(\vec{x}).$$

2) Gradient

If $f(x, y, z)$ is a scalar function of 3 variables

$$f: \mathbb{R}^3 \rightarrow \mathbb{R}$$

$$(x, y, z) \rightarrow f(x, y, z)$$

$$\nabla f(\vec{x}) = \left(\frac{\partial f}{\partial x}(\vec{x}), \frac{\partial f}{\partial y}(\vec{x}), \frac{\partial f}{\partial z}(\vec{x}) \right)$$

3) Laplacian.

$$\Delta f = \nabla^2 f = \nabla \cdot (\nabla f) = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2}$$

Proof.

$$\nabla \cdot (\nabla f) = \nabla \cdot \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z} \right) =$$

$$= \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial x} \right) + \frac{\partial}{\partial y} \left(\frac{\partial f}{\partial y} \right) + \frac{\partial}{\partial z} \left(\frac{\partial f}{\partial z} \right) =$$

$$= \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2} \quad \checkmark$$

Divergence Theorem.

Concept of Region:- An open set containing all or some of the points forming its boundary.

Def.- A closed surface $\partial\Omega$ that consists of a finite number of smooth pieces joined together at the boundaries (curves defining boundaries) is called closed piecewise-smooth surface.

Def.- By a smooth surface S , we mean

$$S: \vec{r} = \vec{r}(u, v), \quad (u, v) \in D.$$

Such that $\vec{r}(u, v)$ is continuously differentiable and its unit normal vector $\hat{n}(\vec{x}_s)$ is continuous on S .

Theorem.-

- a) Ω is a bounded region.
- b) $\partial\Omega$ is the closed piecewise smooth surface of Ω .
- c) $F(\vec{x})$ is continuous on $\Omega \cup \partial\Omega$.
- d) $F(\vec{x})$ is continuously differentiable in Ω .
- e) $\hat{n}(\vec{x}_s)$ is the unit outer normal vector to Ω at $\vec{x}_s$.

Then,

$$\iiint_{\Omega} \nabla \cdot \vec{F}(\vec{x}) dV = \iint_{\partial\Omega} (\vec{F} \cdot \hat{n})(\vec{x}_s) ds.$$

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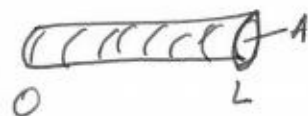
Fundamental theorem of Calculus as a particular case of

Consider the divergence theorem

Divergence theorem.

omit if
not much time

$$\iiint_{\Omega} \nabla \cdot \vec{F} \, dV = \iint_{\partial \Omega} \vec{F} \cdot \hat{n} \, ds$$



1) If $\Omega \equiv$ Finite cylinder of constant cross-section A and length L .

2) If $\vec{F} = (F_1, F_2, F_3) = (F_1, 0, 0)$

and F_1 is constant at any cross section

then $F_1(x, y, z) = \bar{F}_1(x)$

$$\begin{aligned} \text{and } \iiint_{\Omega} \nabla \cdot \vec{F} \, dV &= \iiint_{\Omega} \frac{\partial F_1}{\partial x}(x, y, z) \, dV = A \int_0^L \frac{d\bar{F}_1}{dx} dx = \\ &= A [\bar{F}_1(L) - \bar{F}_1(0)] \quad \checkmark \end{aligned}$$

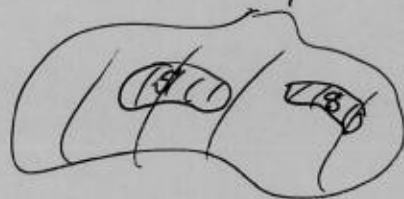
$$\text{Also, } \iint_{\partial \Omega} \vec{F} \cdot \hat{n} \, ds = \iint_{\text{walls}} \vec{F} \cdot \hat{n} \, ds + \iint_{\text{at } x=L} \vec{F} \cdot \hat{n} \, ds + \iint_{\text{at } x=0} \vec{F} \cdot \hat{n} \, ds$$

At walls : $\vec{F} \cdot \hat{n} = (F_1, 0, 0) \cdot \hat{n} = 0$, At $x=L$ $\vec{F} \cdot \hat{n} = \bar{F}_1(L)$
At $x=0$ $\vec{F} \cdot \hat{n} = -\bar{F}_1(0)$

$$\Rightarrow \iint_{\partial \Omega} \vec{F} \cdot \hat{n} \, ds = \bar{F}_1(L) \iint_{x=L} ds - \bar{F}_1(0) \iint_{x=0} ds = A [\bar{F}_1(L) - \bar{F}_1(0)] \quad \checkmark$$

4 (2)

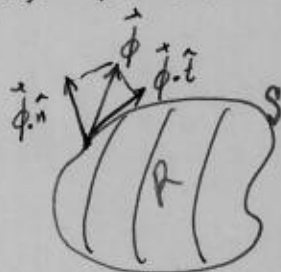
In 2-D or 3-D, Consider an arbitrary region R inside T



Want to study conservation of heat energy inside Region R bounded by surface S .

(I) Heat energy inside R =
$$\iiint_R c(x,y,z) \rho(x,y,z) V(x,y,z,t) dv$$

(II) ϕ or heat flux is now a vector function $\vec{\phi}(x,y,z,t)$.



If $\vec{\phi} \cdot \hat{n} > 0 \Rightarrow \phi$ is directed outward of R
 If $\vec{\phi} \cdot \hat{n} < 0 \Rightarrow \phi$ is directed inward of R
 $\hat{n}$: outward unit normal.

Flux of heat energy out of region R =
$$\iint_S \vec{\phi}(x,y,z,t) \cdot \hat{n}(x,y,z) ds$$

Div thm

$$= \iiint_R \nabla \cdot \vec{\phi}(x,y,z,t) dv$$

$\xrightarrow{R}$ and per unit of time.

Heat energy per unit of Vol. ^{generated} inside R = $Q(x,y,z,t)$.

Therefore, Conservation of energy inside R leads to

$$\frac{\partial}{\partial t} \iiint_R c \rho v dv = \overset{\text{loss?}}{-} \iint_S \vec{\phi} \cdot \hat{n} ds + \iiint_R Q(x,t) dv$$

$$\stackrel{\text{Div Thm}}{=} - \iiint_R \nabla \cdot \vec{\phi} dv + \iiint_R Q dv$$

or

$$\iiint_R \left[c\rho \frac{\partial v}{\partial t} + \nabla \cdot \vec{\phi} - Q \right] dv = 0$$

True for any region R , then

$$c\rho \frac{\partial v}{\partial t} = -\nabla \cdot \vec{\phi} + Q$$

Again, Fourier's law of Heat conduction:

$$\vec{\phi} = -k_0 \nabla v \quad \text{Same physical properties as in 1-D.}$$

$$\Rightarrow \boxed{c\rho \frac{\partial v}{\partial t} = -\nabla \cdot (-k_0 \nabla v) + Q.} \quad (2.1)$$

If thermal conductivity k_0 is constant and $Q=0$. (no sources of heat energy)

$$\frac{\partial v}{\partial t} = k \nabla \cdot (\nabla v)$$

then $\boxed{\frac{\partial v}{\partial t} = k \nabla^2 v}$ Heat or diffusion eqn. (2.2)

Possible BC's.: $v(x, y, z, t) = T(x, y, z, t)$ on boundary S .

$$\frac{\partial v}{\partial n} = \nabla v \cdot \hat{n}(x, y, z, t) = H(x, y, z, t) = \begin{cases} \neq 0 \\ = 0, \text{ insulated.} \end{cases}$$

IC.: $v(x, y, z, 0) = f(x, y, z)$ $\rightarrow$ Equations of elliptic type.

Steady state + No heat sources + Constant thermal properties in (2.1) leads to

If $Q=0$

$$\nabla^2 v = -\frac{Q}{k_0}$$

$$\nabla^2 v = 0,$$

Poisson's eqn.

Laplace's equation.

Discuss analytic techniques and limitations. !

Fourier's Law of heat conduction in Higher dimensions

In 1-d

$$\text{Flux} = \phi(x,t) = -K_0(x) \frac{\partial u}{\partial x}(x,t).$$

In 2-d or 3-d.

The flux is a vector $\vec{\phi}(\vec{x},t) = \vec{\phi}(x,y,z,t)$.

The question is in what direction the heat energy is naturally flowing.

Answer: For isotropic materials, "heat flows from hotter to colder ^{regions} in the direction in which temperature differences are greatest."

So In math terms, heat flows in the direction in which the highest value among all directional derivatives ^{the rate of change of u} is achieved.

$$\vec{\phi}(\vec{x},t) = -K_0(\vec{x}) \nabla u$$

In next two pages, the direction of maximum rate of change is determine.

Rate of change of temperature $u(\vec{x}, t)$ in a given direction $\vec{v}$ ($\|\vec{v}\|=1$) is given by $u(\vec{x}, t)$ directional derivative in the direction of $\vec{v}$.

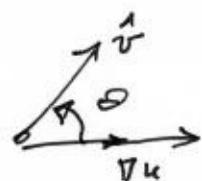
It means

$$D_{\vec{v}} u(\vec{x}, t) = \nabla u(\vec{x}, t) \cdot \vec{v}.$$

This rate of change is the greatest when $\vec{v} = \nabla u$.

In fact,

$$\begin{aligned} \nabla u \cdot \vec{v} &= \|\nabla u\| \|\vec{v}\| \cos \theta \\ &= \|\nabla u\| \cos \theta \end{aligned}$$



This is greatest when $\theta = 0$

$$\Rightarrow \vec{v} = \frac{\nabla u}{\|\nabla u\|}$$



Also, $\vec{\phi}$ is proportional to temp. differences

$$\Rightarrow \vec{\phi}(\vec{x}, t) = -K_0(\vec{x}) \nabla u(\vec{x}, t)$$

Example. - Consider $f(x, y) = x e^y$

- a) Find the directional derivative of $f(x, y)$ at $(2, 0)$ in the direction $(\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}), (\frac{1}{\sqrt{5}}, \frac{2}{\sqrt{5}}), (1, 0), (0, 1), (1, 2)$
- b) In what direction does f have the maximum rate of change? What is the maximum rate of change?

$$D_{(\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}})} f = \nabla f^{(2,0)}(\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}) = (e^y, x e^y) \Big|_{(2,0)} (\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}})$$

$$= (1, 2) \cdot (\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}) = \frac{3}{\sqrt{2}} = \frac{3\sqrt{2}}{2}$$

$$D_{(\frac{1}{\sqrt{5}}, \frac{2}{\sqrt{5}})} f = \nabla f(2, 0) \cdot (\frac{1}{\sqrt{5}}, \frac{2}{\sqrt{5}}) = (1, 2) \cdot (\frac{1}{\sqrt{5}}, \frac{2}{\sqrt{5}}) = \frac{1}{\sqrt{5}} + \frac{4}{\sqrt{5}} = \frac{5}{\sqrt{5}} = \sqrt{5}$$

$$D_{(1,0)} f = \frac{\partial f}{\partial x}(2, 0) = e^0 = 1$$

$$D_{(0,1)} f(2, 0) = \frac{\partial f}{\partial y}(2, 0) = 2$$

Largest value : $\boxed{D_{(\frac{1}{\sqrt{5}}, \frac{2}{\sqrt{5}})} f(2, 0) = \sqrt{5}}$

8 2¹³
b) In general, for $\vec{w}$ s.t. $\|\vec{w}\|=1$

$$D_{\vec{w}} f(x_0, y_0) = \nabla f(x_0, y_0) \cdot \vec{w}$$

but $\nabla f(x_0, y_0) \cdot \vec{w} = \|\nabla f(x_0, y_0)\| \|\vec{w}\| \cos \theta$

$$= \|\nabla f(x_0, y_0)\| \cos \theta$$



Largest value when $\theta=0$.

$\Rightarrow \vec{w}$ is in the direction of $\nabla f(x_0, y_0)$.

$$\vec{w} = \frac{\nabla f}{\|\nabla f\|}$$

In our previous example,

$$\nabla f(2,0) = (e^y, x e^y) \Big|_{(2,0)} = (1, 2).$$

So $(1, 2)$ is the direction of maximum increase.
for $f(x, y)$ at
the point $(2, 0)$

Maximum rate of change:

$$\begin{aligned} D_{\frac{\nabla f(2,0)}{\|\nabla f\|}} f(2,0) &= D_{\left(\frac{1}{\sqrt{5}}, \frac{2}{\sqrt{5}}\right)} f(2,0) = \nabla f(2,0) \cdot \left(\frac{1}{\sqrt{5}}, \frac{2}{\sqrt{5}}\right) \\ &= \sqrt{5}. \checkmark \end{aligned}$$